# Algorithms for lattice QCD I 

Stefan Schaefer

NIC, DESY

Kolkata Lattice Gauge Theory School

## Algorithms in Lattice QCD

## Definition

Using a discrete space-time QCD can be defined.

## Computational method

Path integral $\rightarrow$ high dimensional integral
Computation of integrals by Monte Carlo.
E.g. hadron masses, decay constants, ...

## Algorithms

Many calculations computationally very expensive.
Massively parallel computers employed.
Need to work on simulation setup, algorithms,...
Many choices.
Physics understanding $\leftrightarrow$ Numerical setup.

## Algorithms in Lattice QCD

## Field update

Integral over field variables $\rightarrow$ sum over field
configurations
How to efficiently generate these fields.
Transformation of action into form amenable to numerical treatment.
Numerical solution of diff. eq.

## Solution of Dirac equation

Needed in field update and fermionic observables.
Out-of-the-box algorithms, e.g., the conjugate gradient, perform badly
$\rightarrow$ Need to take physics into account

## Outline

## Monday

Introduction
Markov Chain Monte Carlo
The HMC algorithm
Tuesday
MD integrators
Fermions in QCD simulations
Mass preconditioning

## Outline

## Wednesday

Other fermion methods (RHMC, DD-HMC)
Solution of the Dirac equation

Thursday
Solution of the Dirac equation II
Local deflation
Methods to compute hadron observables

## Friday

Autcorrelations

General reading:
M. Lüscher

Computational strategies in lattice QCD
Les Houches 2009

## Goal



## Computation of path integral

$$
\langle A\rangle=\frac{1}{Z} \int \prod_{x, \mu} d U_{x, \mu} e^{-S[U]} A[U]
$$

with

$$
Z=\prod_{x, \mu} d U_{x, \mu} e^{-S[U]}
$$

One $\operatorname{SU}(3)$ integration variable for each link.

## Goal



$$
\langle A\rangle=\frac{1}{Z} \int \prod_{x, \mu} d U_{x, \mu} e^{-S[U]} A[U]
$$

One $\operatorname{SU}(3)$ integration variable for each link.
$128 \times 64^{3}$ lattice $\rightarrow 1.3 \cdot 10^{8}$ links
Classical numerical quadrature would need
$N^{\# v a r i a b l e s}$ function evaluations

## Monte Carlo

General idea of Monte-Carlo integration

$$
\frac{1}{b-a} \int_{a}^{b} \mathrm{~d} x f(x) \approx \frac{1}{N} \sum_{i=1}^{N} f\left(x_{i}\right)
$$

with randomly chosen points $x_{i}$ in the integration region

- good idea, if $f(x)$ approximately constant $\Rightarrow$ small fluctuations in $f\left(x_{i}\right)$.
- For a given realization of the $N$ points $x_{i}$, this is an unbiased estimator of the integral




## Error of a MC simulation

$$
\tilde{F}_{j}=\frac{1}{N} \sum_{i=1}^{N} f\left(x_{i}^{j}\right)
$$

Index $j$ labels the repetition of the "experiment".
Unbiased = gives correct result on average

$$
F=\langle\langle\tilde{F}\rangle\rangle
$$

$\langle\langle\cdot\rangle\rangle$ average over realizations of the $x_{i}$
Typical deviation $\rightarrow$ variance of this estimator.

$$
\begin{aligned}
\left\langle\left\langle(\tilde{F}-F)^{2}\right\rangle\right\rangle & =\frac{1}{N^{2}} \sum_{i k}\left\langle\left\langle F_{i} F_{k}\right\rangle\right\rangle-F^{2} \\
& \left.=\frac{1}{N}\left(\sum_{i}\left\langle\left(\tilde{( } F_{i}\right)^{2}\right\rangle\right\rangle-F^{2}\right)=\operatorname{var}(F) / N
\end{aligned}
$$

Error decreases as $1 / \sqrt{N}$

## Note of caution

This theoretical analysis assumes knowlege of two quanitites

$$
\bar{F}=\int d x f(x) \quad \text { and } \quad \operatorname{var}(\mathbf{f})=\int d x(f(x)-\bar{f})^{2}
$$

What you get from the Monte Carlo are estimators of these quantities.

The analysis is correct for $N \rightarrow \infty$; $\infty$ is a large number.
These estimators might have significant errors, which are hard to get from the MC. You might also just have been unlucky.

To a certain extend, practical Monte Carlo is an art and requires careful inspection of the results.

## Importance sampling

Estimator correct up to $\sqrt{\operatorname{var}(f) / N} \rightarrow$ reduce variance.

$$
\int \mathrm{d} x f(x)=\int \rho(x) \mathrm{d} x \frac{f(x)}{\rho(x)}=\left[\frac{1}{N} \sum_{i=1}^{N} \frac{f\left(x_{i}\right)}{\rho\left(x_{i}\right)}\right]\left(1+\mathcal{O}\left(N^{-1 / 2}\right)\right)
$$

with points $x_{i}$ chosen according to $\rho$.

- Choose points accoring to probablity distribution similar to function to be integrated
- optimal, if distribution $\propto|f(x)| \ldots$ need $\int d x|f(x)|$



## Markov Chain Monte Carlo

Problem of "straight" Monte Carlo is to find a normalized probability density $P(x)$

Solution
Use a method which only needs relative probabilites
Construct a sequence of points

$$
x_{1} \rightarrow x_{2} \rightarrow x_{3} \rightarrow \cdots \rightarrow x_{N}
$$

using a transition probability $T\left(x_{i+1} \leftarrow x_{i}\right)$
Analysis using arguments of a $N$ sets of such chains.

## Properties of $T$

For any given pair of points $x_{1}$ and $x_{2}$

$$
T\left(x_{2} \leftarrow x_{1}\right)
$$

with the following properties
(A) Stability

$$
P\left(x^{\prime}\right)=\int d x P(x) T\left(x^{\prime} \leftarrow x\right)
$$

(B) Normalization

$$
\int d x^{\prime} T\left(x^{\prime} \leftarrow x\right)=1
$$

(C) Ergodicity

$$
T\left(x^{\prime} \leftarrow x\right)>0 \text { for each pair } x, x^{\prime}
$$

No reference to absolute normalization of $P$

## Analysis of MCMC

For the sake of simplicity, consider discrete state space. Integrals $\rightarrow$ sums.

Example for a single variable with three possible values:

$T\left(x^{\prime} \leftarrow x\right)$ is a matrix acting in the space of states.
For the example a $3 \times 3$ matrix, because $x$ can take 3 values.
A probability distribution is a normalized vector in this space.

## Analysis of MCMC

Imagine having an ensemble of points $x_{i}$ distributed according to $P(x)$.

Condition (A) reads

$$
P=T P
$$

$\rightarrow P$ is eigenvector of $T$ with eigenvalue 1.

## Theorem of Frobenius-Perron

For a matrix with the properties $\mathrm{A}-\mathrm{C}$ the following holds

- There is exactly one eigenvalue $\lambda=1$.
- All eigenvalues $\lambda$ have $|\lambda| \leq 1$.


## Convergence of Markov Process

Given any starting distribution $P_{0}$ repeated application of $T$ leads to exponential convergence to desired distribution

$$
\begin{aligned}
T^{n} P_{0} & =\sum_{i=0}^{N} \lambda_{i}^{n}\left(\Psi_{i}, P_{0}\right) \Psi_{i} \\
& =\sum_{i=0}^{N} e^{\log \left|\lambda_{i}\right| n}\left(\Psi_{i}, P_{0}\right) \frac{\lambda_{i}}{\left|\lambda_{i}\right|} \Psi_{i} \\
& \propto P+\mathbf{O}\left(e^{-n / \tau_{1}}\right)
\end{aligned}
$$

$\tau_{i}=1 / \log \left|\lambda_{i}\right|$ are the exponential autocorrelation times A nicer interpretation in terms of single exponentials can be given with detailed balance, see later.

## Practical MCMC

Start with one (or a few) points Averages of Monte Carlo time

$$
\langle f\rangle=\frac{1}{N} \sum_{i=1}^{N} f\left(x_{i}\right)
$$



Cut away first thermalization phase.

## Time evolution



$$
\langle f\rangle=\frac{1}{N} \sum_{t=1}^{N} f\left(x_{i}\right)(1+\mathcal{O}(1 / \sqrt{N}))
$$

At the beginning large contributions from $\Psi_{i>0}$.
Formally, they are supressed by $1 / N$, but they are best not considered.
A valid simulation must have $n \gg 1 / \tau_{1}$

## Autocorrelations

There is a price to pay:
Subsequent points $x_{i}$ /configurations are in general not independent.

$$
\left\langle\left\langle f\left(x_{i}\right) f\left(x_{i+1}\right)\right\rangle\right\rangle \neq 0
$$

This needs to be taken into account in the analysis of the data.

It also can make simulations exceedingly expensive.


## Construction of $T$

Constructing a valid $T$ seems a daunting task. Metropolis-Hastings method

- Symmetric proposal (trans. prob. w/ $P_{0}(x)=$ const)

$$
W\left(x^{\prime} \leftarrow x\right)=W\left(x \leftarrow x^{\prime}\right)
$$

- Acceptance step

$$
P_{a c c}\left(x^{\prime}, x\right)=\min \left[1, \frac{P\left(x^{\prime}\right)}{P(x)}\right]
$$

Next point is $x^{\prime}$ with propability $P_{\text {acc }}$, else $x$
Total transition propability
$T\left(x^{\prime} \leftarrow x\right)=W\left(x^{\prime} \leftarrow x\right) P_{a c c}\left(x^{\prime}, x\right)+\delta_{x x^{\prime}} \sum_{\tilde{x}}\left(1-P_{a c c}(\tilde{x}, x)\right) W(\tilde{x} \leftarrow x)$

## Proof

$$
T\left(x^{\prime} \leftarrow x\right)=W\left(x^{\prime} \leftarrow x\right) P_{\text {acc }}\left(x^{\prime}, x\right)+\delta_{x x^{\prime}}\left[\sum_{\tilde{x}}\left(1-P_{a c c}(\tilde{x}, x)\right) W(\tilde{x} \leftarrow x)\right]
$$

(A) Stability

$$
\begin{aligned}
& \sum_{x} P(x) T\left(x^{\prime} \leftarrow x\right) \\
& \left.=\sum_{x} W\left(x^{\prime} \leftarrow x\right) P(x) P_{\text {acc }}\left(x^{\prime}, x\right)+P\left(x^{\prime}\right) \sum_{\tilde{x}}\left(1-P_{\text {acc }}(\tilde{x}, x)\right) W(\tilde{x} \leftarrow x)\right] \\
& =\sum_{x} W\left(x \leftarrow x^{\prime}\right) P\left(x^{\prime}\right) P_{\text {acc }}\left(x, x^{\prime}\right)+P\left(x^{\prime}\right)\left(1-\sum_{\tilde{x}} P_{\text {acc }}(\tilde{x}, x) W(\tilde{x} \leftarrow x)\right]=P\left(x^{\prime}\right)
\end{aligned}
$$

(B) Normalization

$$
\sum_{x^{\prime}} T\left(x^{\prime} \leftarrow x\right)=1
$$

## Practical implementation

We want to generate the sequence

$$
x_{1} \rightarrow x_{2} \rightarrow x_{3} \rightarrow \cdots
$$

and arrived at $x_{j}$

- Make a proposal $y$ according to probability $W\left(y \leftarrow x_{j}\right)$
- Compute $P_{\text {acc }}$ and draw random number $0 \leq r<1$

$$
x_{j+1}= \begin{cases}y & \text { if } r<P_{\mathrm{acc}} \\ x_{j} & \text { else }\end{cases}
$$

Good proposal

- Easy to generate
- High acceptance propability


## Generic issues of the method

The step size can be rather limited

## Small steps

$P\left(x^{\prime}\right) \approx P(x) \rightarrow P_{\text {acc }}$ high
But it take many steps to sample the whole integration space
Large autocorrelations

## Large steps

Small autocorrelations
Feasible only if an update leading to reasonable $P_{\text {acc }}$ can be found
Can be difficult to compute proposal.
In high dimensional spaces, it can be very difficult to argue, what "large step" and "small step" even mean.

## Summary of part I

Monte Carlo is a method to numerically compute high-dimensional integrals.

Integral $\rightarrow$ average over sample points.
Sample points need to be chosen in region of high probability.

Problem of constructing a normalized distribution
$\rightarrow$ Markov Chain Monte Carlo
No normalized distribution needed.
Deal with autocorrelations.

## Back to QCD



One point $x \rightarrow$ one value for each link variable $\rightarrow$ one field configuration

Instead of $x$ we will therefore now use $U$ which are in $\mathrm{SU}(3)$.

$$
\langle A\rangle=\frac{1}{Z} \int \prod_{x, \mu} d U_{x, \mu} e^{-S[U]} A[U]
$$

with

$$
Z=\prod_{x, \mu} d U_{x, \mu} e^{-S[U]}
$$

Normalized probability density

$$
P[U]=\frac{1}{Z} e^{-S[U]}
$$

Ratios in probabilities
$\rightarrow$
Need to evaluate differences in the action $S[U]$ While this choice of $P[U]$ seems natural, it is not unique

## QCD

Basically two types of algorithms

## Single link updates

Of the $4 V$ links, only one is changed at a time.
In each step $S[U]-S\left[U^{\prime}\right]$
Possible if this is an $\mathrm{O}(1)$ operation.
With dynamical fermions, estimating change in action is a global $\mathrm{O}(V)$ operation

Method of choice in pure gauge theory.
No systematic study.

## QCD

Basically two types of algorithms
Updates based on Molecular Dynamics
Based on ideas from classical mechanics.


Field configuration position Introduce momenta $\rightarrow$ equations of motion.
Updates keep propbability constant (micro-canonical)
Solves problem of finding a good proposal in
Metropolis-Hastings procedure

## Hybrid Monte Carlo

## Extended field space

$$
Z=\int[d U][d \pi] e^{-\frac{1}{2}(\pi, \pi)-S[U]}
$$

Expectation values of observables $A[U]$ remain the same.

Momenta $\pi=\pi^{a} T^{a} \in \operatorname{su}(N), \pi^{a} \in \mathbb{R}$

$$
(\pi, \pi)=\sum_{x, \mu} \pi_{x, \mu}^{a} \pi_{x, \mu}^{a}
$$

## Updates

Make updates in this extended phase space.
$\Rightarrow$ updates for $U$ fields.

## Molecular dynamics

Essential update step for the gauge fields: $(\pi, U) \rightarrow\left(\pi^{\prime}, U^{\prime}\right)$

## Hamilton's equations of motion

Hamiltonian

$$
H[\pi, U]=\frac{1}{2}(\pi, \pi)+S[U]
$$

E.o.m.

$$
\begin{aligned}
\dot{U}_{x, \mu} & =\pi_{x, \mu} U_{x, \mu} \\
\dot{\pi}_{x, \mu} & =-F_{x, \mu}
\end{aligned}
$$

$$
F_{x, \mu}^{a}=\frac{\partial \boldsymbol{S}\left(e^{\omega} U\right)}{\partial \omega^{a}(x, \mu)}
$$

## Molecular dynamics

By Liouville's theorem, the classical dynamics

$$
(\pi, U) \rightarrow\left(\pi^{\prime}, U^{\prime}\right)
$$

maps areas of equal likelihood into eachother.
Energy conservation

$$
\frac{d}{d \tau} H=0
$$

Boltzmann factor $e^{-H}$ is constant.

Conservation of phase space

An exact solution of the E.o.m is a valid update.
Fundamentally different from Metropolis-Hastings
In practice: integration errors

## HMC

## Momentum Heatbath

Refresh momenta $\pi$ (Gaussian random numbers)

## Molecular Dynamics

Solve numerically MD equations for some MC time $\tau$ (trajectory) deriving from Hamiltonian $H=\frac{1}{2}(\pi, \pi)+S[U]$.


## Acceptance Step

Correcting for inaccuracies in integration.

## Metropolis

Different viewpoint:
The molecular dynamics as the symmetric proposal in Metropolis.

This solves the problem of the inexact integration.
Need a symplectic integrator, i.e. area conserving and reversible.

Reversibility haunts computer implementations. No good theory for this.

## Metropolis

## Acceptance step

Molecular dynamics $(\pi, U) \rightarrow(\bar{\pi}, \bar{U})$

$$
P_{\mathrm{acc}}=\min \left(1, e^{-(H(\bar{\pi}, \bar{U})-H(\pi, U))}\right)
$$

Exact solution of MD equations has $\Delta H=0$
$\Rightarrow$ always accepted
$\Delta H$ needs to be $\mathrm{O}(1)$ for good acceptance. Difficult to achieve on large volume.

## Updates

$$
Z=\int[d U][d \pi] e^{-\frac{1}{2}(\pi, \pi)-S[U]}
$$

## Momenta: Heatbath

- $(\pi, \pi)=\sum_{x, \mu}\left|\pi_{x, \mu}^{a}\right|^{2}$
$\pi^{a}$ are Gaussian random numbers.
■ Normalization is known.
Just for $\pi$ this is the optimal update no correlation to previous config. Also true for combined system? (Kramers' rule,... )


## Comments

Momentum heat-bath is the only source of randomness.
Makes algorithm ergodic.
Problems with ergodicity from $S=\infty$ surfaces.

The original hope was that a trajectory consititutes a macroscopic update.

Free field theory

$$
\ddot{U}=\dot{\pi}=\frac{\delta S}{\delta U}
$$

$\rightarrow$ Monte Carlo Time $\tau \propto 1 / a$

In the classic algorithm trajectory length is scaled with $1 / a$.
In number of updates, autocorrelations should stay the same.
M.Lüscher, S.S.'11

This does not apply in interacting theory
$\rightarrow$ Wednesday
Virotta,Sommer, S.S.' 10
Still, rather long trajectories are a good idea, $\tau \sim 2$.

For exercises in $\phi^{4}$ theory: S.S., Les Houches 2009, available at NIC@DESY website.

